Configurable damper actuator for adjusting dampers in technical building installations

- Air damper size up to approx. $0.8 \mathrm{~m}^{2}$
- Torque motor 4 Nm
- Nominal voltage AC/DC 24 V
- Control modulating 2... 10 V variable
- Position feedback 2... 10 V variable
- Running time motor 2.5 s variable



## Technical data

| Electrical data | Nominal voltage | AC/DC 24 V |
| :---: | :---: | :---: |
|  | Nominal voltage frequency | $50 / 60 \mathrm{~Hz}$ |
|  | Nominal voltage range | AC 19.2...28.8 V / DC 21.6...28.8 V |
|  | Power consumption in operation | 13 W |
|  | Power consumption in rest position | 2 W |
|  | Power consumption for wire sizing | 23 VA |
|  | Power consumption for wire sizing note | Imax $20 \mathrm{~A} @ 5 \mathrm{~ms}$ |
|  | Connection supply / control | Cable $1 \mathrm{~m}, 4 \times 0.75 \mathrm{~mm}^{2}$ |
|  | Parallel operation | Yes (note the performance data) |
| Functional data | Torque motor | 4 Nm |
|  | Torque variable | 25\%, 50\%, 75\% reduced |
|  | Operating range $Y$ | 2... 10 V |
|  | Input Impedance | $100 \mathrm{k} \Omega$ |
|  | Operating range $Y$ variable | Start point $0.5 . . .30 \mathrm{~V}$ <br> End point 2.5... 32 V |
|  | Options positioning signal | Open/close <br> Modulating (DC $0 . . .32 \mathrm{~V}$ ) |
|  | Position feedback U | 2... 10 V |
|  | Position feedback U note | Max. 0.5 mA |
|  | Position feedback U variable | Start point 0.5 ... 8 V <br> End point 2.5... 10 V |
|  | Position accuracy | $\pm 5 \%$ |
|  | Direction of motion motor | selectable with switch 0/1 |
|  | Direction of motion note | $\mathrm{Y}=0 \mathrm{~V}$ : At switch position 0 (ccw rotation) / <br> 1 (cw rotation) |
|  | Direction of motion variable | electronically reversible |
|  | Manual override | with push-button, can be locked |
|  | Angle of rotation | Max. $95^{\circ}$ |
|  | Angle of rotation note | can be limited on both sides with adjustable mechanical end stops |
|  | Minimum angle of rotation | Min. $30^{\circ}$ |
|  | Running time motor | $2.5 \mathrm{~s} / 90^{\circ}$ |
|  | Running time motor variable | 2.5 ... 10 s |
|  | Adaptation setting range | manual (automatic on first power-up) |
|  | Adaptation setting range variable | No action <br> Adaptation when switched on Adaptation after pushing the gear disengagement button |
|  | Override control | $\begin{aligned} & \text { MAX (maximum position })=100 \% \\ & \text { MIN (minimum position) }=0 \% \\ & \text { ZS (intermediate position, AC only) }=50 \% \end{aligned}$ |


| Functional data | Override control variable | $\begin{aligned} & \text { MAX }=(\text { MIN }+32 \%) . . .100 \% \\ & \text { MIN }=0 \% . . .(\text { MAX }-32 \%) \\ & \text { ZS }=\text { MIN...MAX } \end{aligned}$ |
| :---: | :---: | :---: |
|  | Sound power level, motor | $54 \mathrm{~dB}(\mathrm{~A})$ |
|  | Mechanical interface | Universal shaft clamp 8... 26.7 mm |
|  | Position indication | Mechanically, pluggable |
| Safety data | Protection class IEC/EN | III, Safety Extra-Low Voltage (SELV) |
|  | Power source UL | Class 2 Supply |
|  | Degree of protection IEC/EN | IP54 |
|  | Degree of protection NEMA/UL | NEMA 2 |
|  | Enclosure | UL Enclosure Type 2 |
|  | EMC | CE according to 2014/30/EU |
|  | Low voltage directive | CE according to 2006/95/EC |
|  | Certification IEC/EN | IEC/EN 60730-1 and IEC/EN 60730-2-14 |
|  | Certification UL | cULus according to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1 |
|  |  | The UL marking on the actuator depends on the production site, the device is UL-compliant in any case |
|  | Mode of operation | Type 1 |
|  | Rated impulse voltage supply / control | 0.8 kV |
|  | Pollution degree | 3 |
|  | Ambient temperature | $-30 . .40^{\circ} \mathrm{C}$ |
|  | Ambient temperature note | Caution: $+40 \ldots+50^{\circ} \mathrm{C}$ utilisation possible only under certain restrictions. Please contact your supplier. |
|  | Storage temperature | $-40 . . .80^{\circ} \mathrm{C}$ |
|  | Ambient humidity | Max. 95\% RH, non-condensing |
|  | Servicing | maintenance-free |
| Weight | Weight | 0.99 kg |

## Safety notes

- The device must not be used outside the specified field of application, especially not in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the device and that it is ensured that the ambient conditions remain within the thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- Self adaption is necessary when the system is commissioned and after each adjustment of the angle of rotation (press the adaption push-button once).
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section, the design, the installation situation and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed. position defined by the positioning signal. Measuring voltage $U$ serves for the electrical display of the damper position $0.5 . . .100 \%$ and as slave control signal for other actuators.

Parametrisable actuators The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU.

Simple direct mounting Simple direct mounting on the damper shaft with a universal shaft clamp, supplied with an antirotation device to prevent the actuator from rotating.

Manual override Manual override with push-button possible (the gear is disengaged for as long as the button is pressed or remains locked).

Adjustable angle of rotation
Adjustable angle of rotation with mechanical end stops. A minimum permissible angle of rotation of $30^{\circ}$ must be allowed for.

High functional reliability The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.

Home position The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out an adaption, which is when the operating range and position feedback adjust themselves to the mechanical setting range.
The detection of the mechanical end stops enables a gentle approach to the end positions, thus protecting the actuator mechanics.
The actuator then moves into the position defined by the positioning signal.

Adaptation and synchronisation An adaption can be triggered manually by pressing the "Adaption" button or with the PC-Tool. Both mechanical end stops are detected during the adaption (entire setting range).
Automatic synchronisation after pressing the gearbox disengagement button is configured. The synchronisation is in the home position (0\%).
The actuator then moves into the position defined by the positioning signal.
A range of settings can be adapted using the PC-Tool (see MFT-P documentation)

## Accessories

| Electrical accessories | Description | Type |
| :--- | :--- | :--- |
|  | Positioner for wall mounting | CRP24-B1 |
|  | Feedback potentiometer $10 \mathrm{k} \Omega$ add-on | P10000A |
|  | Feedback potentiometer $1 \mathrm{k} \Omega$ add-on | P1000A |
|  | Feedback potentiometer $140 \Omega$ add-on | P140A |
|  | Feedback potentiometer $200 \Omega$ add-on | P200A |
|  | Feedback potentiometer $2.8 \mathrm{k} \Omega$ add-on | P2800A |
|  | Feedback potentiometer $5 \mathrm{k} \Omega$ add-on | P5000A |
|  | Feedback potentiometer $500 \Omega$ add-on | P500A |
|  | Auxiliary switch $1 \times$ SPDT add-on | S1A |
|  | Auxiliary switch $2 \times$ SPDT add-on | S2A |
|  | Positioner for wall mounting | SGA24 |
|  | Positioner for built-in mounting | SGF24 |
|  | Positioner for front-panel mounting | Z-SPA |
|  | Adapter for auxiliary switch and feedback potentiometer | Z-UIC |


| Mechanical accessories | Description | Type |
| :---: | :---: | :---: |
|  | Angle of rotation limiter for K-NA and K-SA | 20334-00001 |
|  | Actuator arm for standard shaft clamp (one-sided) | AH-25 |
|  | Shaft extension 240 mm Ø 20 mm for damper shaft $\varnothing 8 . . .22 .7 \mathrm{~mm}$ | AV8-25 |
|  | Shaft clamp one-sided, clamping range $\varnothing 8 . . .26 \mathrm{~mm}$ with insert, Multipack 20 pcs. | K-ENMA |
|  | Shaft clamp one-sided, clamping range $\emptyset 8 . . .26$ mm, Multipack 20 pcs. | K-ENSA |
|  | Shaft clamp reversible, clamping range $\varnothing 8 . . .20 \mathrm{~mm}$ | K-NA |
|  | Ball joint suitable for damper crank arm KH8 / KH10 | KG10A |
|  | Ball joint suitable for damper crank arm KH8 | KG8 |
|  | Damper crank arm Slot width 8.2 mm , clamping range Ø10... 18 mm | KH8 |
|  | Anti-rotation mechanism 180 mm , Multipack 20 pcs. | Z-ARS180 |
|  | Base plate extension for NM..A to NM.., pcs. | Z-NMA |
|  | Position indicator, Multipack 20 pcs. | Z-PI |
|  | Form fit insert $10 \times 10 \mathrm{~mm}$, Multipack 20 pcs . | ZF10-NSA |
|  | Form fit insert $12 \times 12 \mathrm{~mm}$, Multipack 20 pcs . | ZF12-NSA |
|  | Form fit insert $15 \times 15 \mathrm{~mm}$, Multipack 20 pcs . | ZF15-NSA |
|  | Form fit insert $16 \times 16 \mathrm{~mm}$, Multipack 20 pcs . | ZF16-NSA |
|  | Form fit insert $8 \times 8 \mathrm{~mm}$, Multipack 20 pcs. | ZF8-NMA |
|  | Mounting kit for linkage operation for flat installation | ZG-NMA |
| Service tools | Description | Type |
|  | Adapter for Service-Tool ZTH | MFT-C |
|  | Belimo PC-Tool, Software for adjustments and diagnostics | MFT-P |
|  | Connection cable $5 \mathrm{~m}, \mathrm{~A}$ : RJ11 6/4 ZTH EU, B: 6-pin for connection to service socket | ZK1-GEN |
|  | Connection cable $5 \mathrm{~m}, \mathrm{~A}$ : RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal | ZK2-GEN |
|  | Service Tool, with ZIP-USB function, for parametrisable and communicative Belimo actuators, VAV controller and HVAC performance devices | ZTH EU |
|  | * Adapter Z-SPA |  |
|  | It is imperative that this adapter will be ordered if an auxiliary switch or a potentiometer is required and if at the same time the shaft clamp is install the actuator (e.g. with short-axis installation). | eedback <br> d on the rear side of |

## Electrical installation



Supply from isolating transformer.
Parallel connection of other actuators possible. Observe the performance data.

Wiring diagrams
AC/DC 24 V , modulating


## Cable colours:

1 = black
2 = red
3 = white
5 = orange

Signal cable lengths


| $\mathrm{L}_{2}$ | $\mathrm{~L}_{\text {tot }}=\mathrm{L}_{1}+\mathrm{L}_{2}$ |  |
| :---: | :---: | :---: |
| $\boldsymbol{\perp / \sim}$ | AC | DC |
| $0.75 \mathrm{~mm}^{2}$ | $\leq 30 \mathrm{~m}$ | $\leq 5 \mathrm{~m}$ |
| $1.00 \mathrm{~mm}^{2}$ | $\leq 40 \mathrm{~m}$ | $\leq 8 \mathrm{~m}$ |
| $1.50 \mathrm{~mm}^{2}$ | $\leq 70 \mathrm{~m}$ | $\leq 12 \mathrm{~m}$ |
| $2.50 \mathrm{~mm}^{2}$ | $\leq 100 \mathrm{~m}$ | $\leq 20 \mathrm{~m}$ |



A = Actuator
C = Control unit (controlling unit)
L1 = Connecting cable of the
actuator

## Note:

There are no special restrictions on installation if the supply and the data cable are routed separately.

A = Actuator
C = Control unit (controlling unit)
L1 = Connecting cable of the actuator
L2 = Customer cable
Ltot = Maximum signal cable length

## Note:

When several actuators are connected in parallel, the maximum signal cable length must be divided by the number of actuators.

## Functions

Functions with basic values (conventional mode)

Override control with AC 24 V with relay contacts


Minimum limit with positioner SG..


Follow-up control (position-dependent)


Functional check

## Procedure

1. Connect 24 V to connections 1

and 2
2. Disconnect connection 3:

- with direction of rotation 0 :

Actuator rotates to the left

- with direction of rotation 1:

Actuator rotates to the right
3. Short-circuit connections 2
and 3 :

- Actuator runs in opposite
direction

Control with $4 \ldots 20 \mathrm{~mA}$ via external resistor


## Caution:

The operating range must be set to DC $2 . . .10 \mathrm{~V}$.
The $500 \Omega$ resistor converts the
4... 20 mA current signal to a voltage signal DC $2 . . .10 \mathrm{~V}$

Functions for actuators with specific parameters (Parametrisation necessary)

Override control and limiting with AC 24 V with relay contacts


Control open/close


Override control and limiting with AC 24 V with rotary switch


1) Caution: This function is only guaranteed if the start point of the operating range is defined as $\min .0 .5 \mathrm{~V}$.


Direction of rotation switch
Switch over: Direction of rotation changes
(2) Push-button and LED display green

Off: No power supply or malfuntion
On: In operation
Press button: Triggers angle of rotation adaptation, followed by standard mode

## (3) Push-button and LED display yellow

Off: Standard mode
On: Adaptation or synchronising process active
Press button: No function
(4) Gear disengagement button

Press button: Gear disengages, motor stops, manual override possible
Release button: Gear engages, synchronisation starts, followed by standard mode

## (5) Service plug

For connecting parameterisation and service tools

## Check power supply connection

2 Off and 3 On Possible wiring error in power supply

## Installation notes

Negative torque Max. 50\% of the torque (Caution: Application possible only with restrictions. Please contact your supplier.)

## Service

## Service Tools connection

The actuator can be parametrised by ZTH EU via the service socket. For an extended parametrisation the PC tool can be connected.

Connection ZTH EU / PC-Tool


Dimensions

## Dimensional drawings



Clamping range

|  | 〇I | $\square I$ | $\diamond I$ |
| :--- | :---: | :---: | :---: |
| $\square$ | $8 \ldots 26.7$ | $\geq 8$ | $\leq 26.7$ |
| $\square$ | $8 \ldots 20$ | $\geq 8$ | $\leq 20$ |
|  |  |  |  |

*Option: Shaft clamp mounted below (accessories K-NA needed)
*Option: Shaft clamp mounted below: If an auxiliary switch or a feedback potentiometer is used the adapter Z-SPA is required.

## Shaft length



Min. 40

Min. 20

